### 0. Name (2 pts):

# AME 3623: Embedded Real-Time Systems

### Midterm Exam Solution Set

March 12, 2013

Topic	Max	Grade
Name	2	
Number Systems	25	
Analog Processing	30	
Microcontrollers	20	
Digital Input/Output	25	
Total	100	

#### 1. Number Systems

(25 pts)

(a) (5 pts) Given the decimal number 228. What is the binary equivalent? Show your work.

Answer: 11100100

(b) (5 pts) Consider the following number: 0xFE. If we interpret this as a signed 8-bit integer, what is the decimal equivalent? Show your work.

$$0xFE = 0b111111110 = -128 + 64 + 32 + 16 + 8 + 4 + 2 = -2$$

(c) (5 pts) Consider the following number: 0xA3. If we interpret this as an unsigned 8-bit integer, what is the decimal equivalent? Show your work.

$$0xA3 = 10 * 16 + 3 = 163$$

(d) (5 pts) Consider the following number: 0x38. Interpret this as a signed 8-bit integer. What is the negative of this number in binary? Show your work.

$$0x38 = 00111000$$
  
Flip: 11000111  
Add 1: 11001000

(e) (5 pts) Consider the following code:

What is the value of y in hexadecimal after the code executes? y=0x10

#### 2. Analog Processing

(30 pts)

Given the following circuit:

$$\stackrel{\mathbf{I_D}}{\longrightarrow} \stackrel{\mathbf{I_1}}{\longrightarrow}$$

Assume that  $R = 1000\Omega$  and  $V_f = 2V$ .

(a) (6 pts) What are the equations that are always true?

$$V_1 - 5 = I_1 R$$
  
 $V_1 - 0 = I_2 R$   
 $I_D = I_1 + I_2$ 

(b) (12 pts) Assume  $V_0 = 3V$ . What is  $V_1$ ?

Guess:  $I_D = 0$  and  $V_0 - V_1 < V_f$ Therefore:

$$0 = I_{D}$$

$$= I_{1} + I_{2}$$

$$= \frac{V_{1} - 5}{R} + \frac{V_{0}}{R}$$

$$= \frac{2V_{1} - 5}{R}$$

$$V_1 = 2.5 V$$

Check: 
$$V_0 - V_1 < V_f$$
  
  $3 - 2.5 < 2$  Correct!

(c) (12 pts) Assume  $V_0=6V.$  What is  $I_D$ ?

Guess:  $I_D > 0$  and  $V_0 - V_1 = V_f$ Therefore:

$$V_1 = V_0 - V_f$$
= 6 V - 2 V
= 4 V

$$I_D = I_1 + I_2$$

$$= \frac{2V_1 - 5}{R}$$

$$= \frac{2 \times 4 - 5}{1000}$$

$$= 3 mA$$

3. Microcontrollers (20 pts)

(a) (8 pts) Give two examples for how the status register is used by other parts of the microprocessor.

Used by the ALU when adding with a carry.

Can be used when updating the value stored in the program counter (a conditional jump).

- (b) (7 pts) When the microprocessor is storing a value into a memory, what two numbers are communicated from the microprocessor to the memory?
  - i. the value to be stored, and
  - ii. the address.
- (c) (5 pts) True or False, and briefly explain: the following code results in a change in what is stored in the ROM.

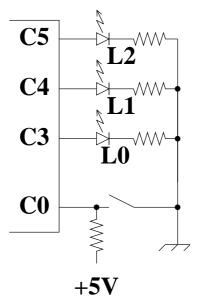
$$x = 42;$$

False. A ROM can't be changed.

## 4. Digital Input/Output

(25 pts)

Consider the following circuit diagram:



(a) (5 pts) Given the circuit, how should DDRC be initialized? (there is only one good answer for initialization)

DDRC = 0x38;

```
Consider the following code:
int main (void)
{
 DDRC = ****; // However you initialized it above.
 PORTC = 0;
  int8_t val = 1;
  while (1)
    PORTC = (PORTC \& 0xE7) \mid (val << 3);
    if (PINC & 0x1) {
      val = 3;
      delay_ms(10);
    }else{
      val = 1;
      if(val < 0) {
        val = 2;
      delay_ms(100);
  }
}
```

(b) (10 pts) Explain what happens to the LEDs when the switch is "closed" from the beginning of the program.

Note 1: val proceeds through the sequence: 1,0,2,1,0,..., with 100 ms for each step Note 2: val only affects LED 0 and 1 (LED 2 is never turned on at any time)

LEDs 0 and 1 flash at a period of 300ms and 33% duty cycle. Their "on" periods do not overlap. LED 2 stays off the entire time.

(c) (10 pts) Explain what happens to the LEDs when the switch is "opened" from the beginning of the program.

Note: val proceeds through the sequence: 1, 2, 1, 2, 1, ..., with 10 ms for each step

LEDs 0 and 1 flash at a period of 20ms with a 50% duty cycle. They flash out of phase. LED 2 stays off the entire time.