

# Getting Started with the Teensy Circuits and Programming

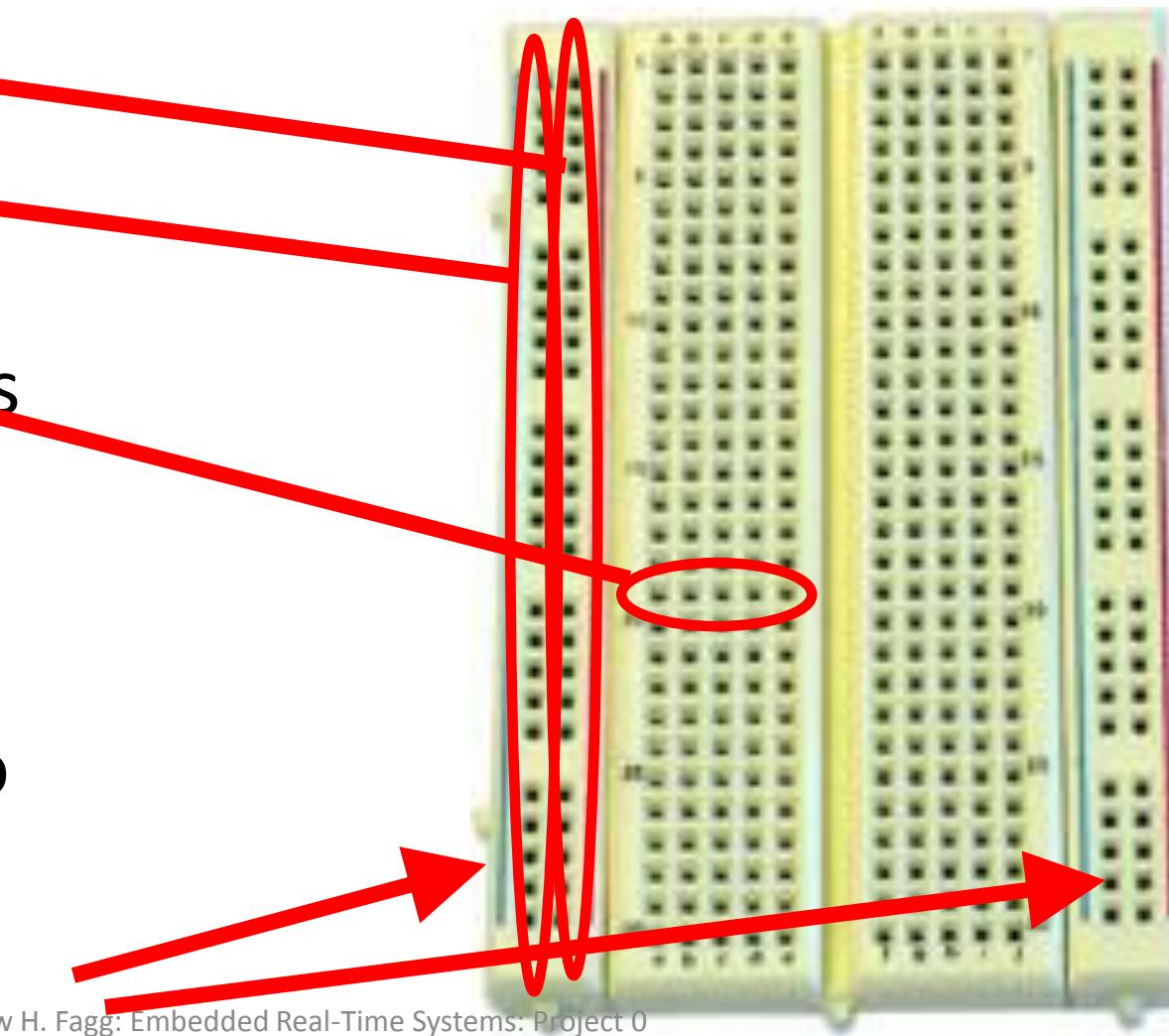
# Solderless Breadboards

Power bus (red)

Ground bus

(blue)  
Component bus

Note that the two  
sides are not  
connected



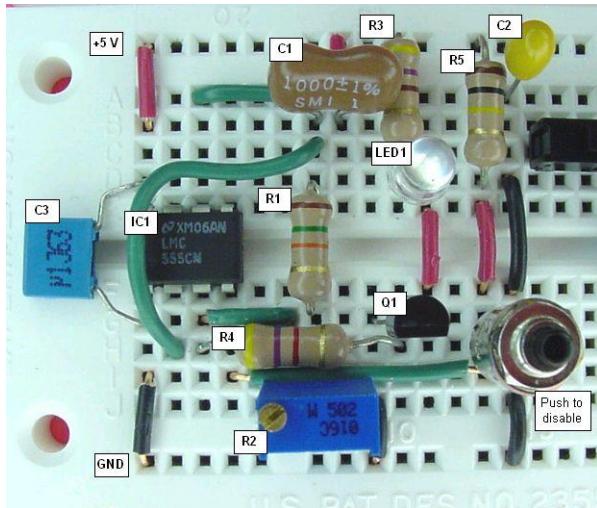
# Wiring Standards

When possible, use wire colors for different types of signals. The common color assignments are:

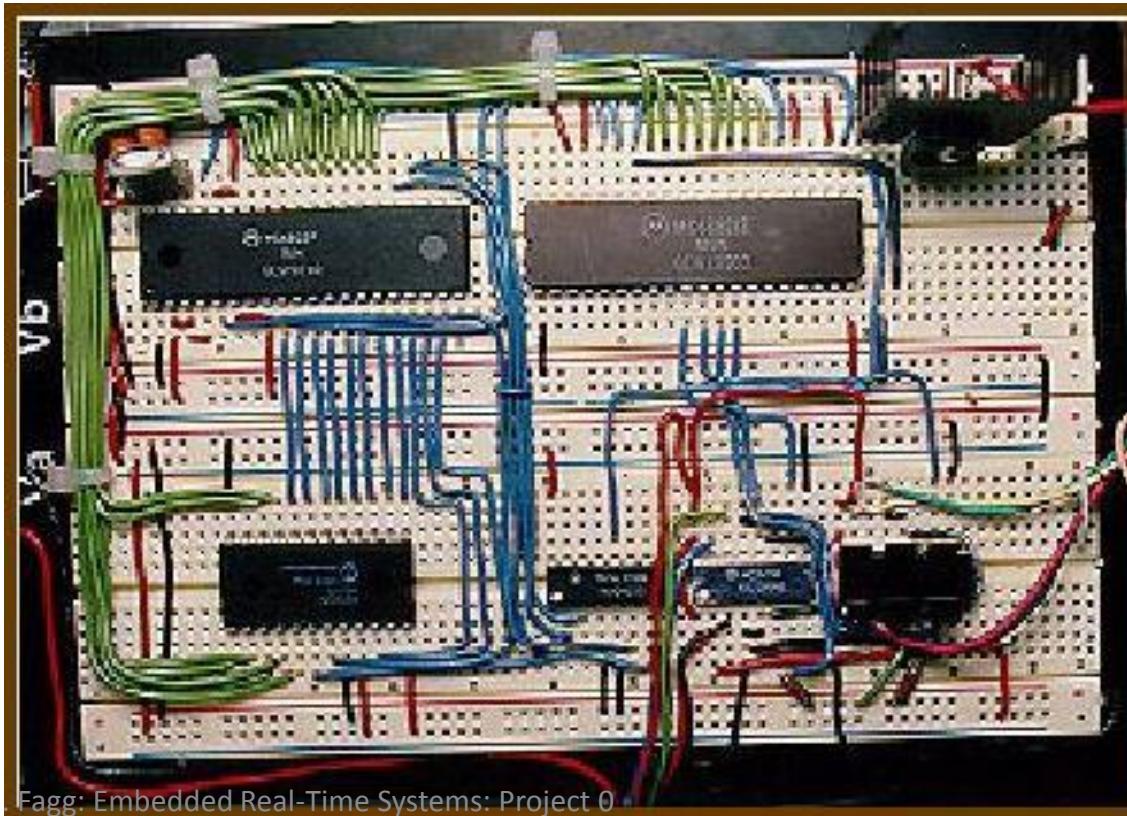
- Black: ground
- Red: power
- Other: various signals

# Clean Wiring

A clean breadboard will make debugging easier – and it makes circuits more robust



[www.linefollowing.com](http://www.linefollowing.com)



tangentsoft.net

Andrew H. Fagg: Embedded Real-Time Systems: Project 0

# Care with Power

- Only insert components and wires into the breadboard when power is disconnected
- “Wire, check-twice, then power”
  - Never reverse power and ground (this is a very common mistake)

# Care with Power

We are using a mixture of 3.3V and 5V components

- Be careful: we can't always mix and match
- The teensy is powered by connecting 5V to Vin and GND to GND (these lines come from the lower deck)
- The teensy can provide 3.3V supply (up to 250mA)
- Even though the teensy uses 3.3V as its base voltage, it is 5V tolerant (but not all 3.3V components will be)
- USB connection does not provide power – only communication

# Suggested Wiring Procedure

- Power supply
- Power/ground buses
- Insert primary components
- Wire power/ground for components
- Add signals and remaining components

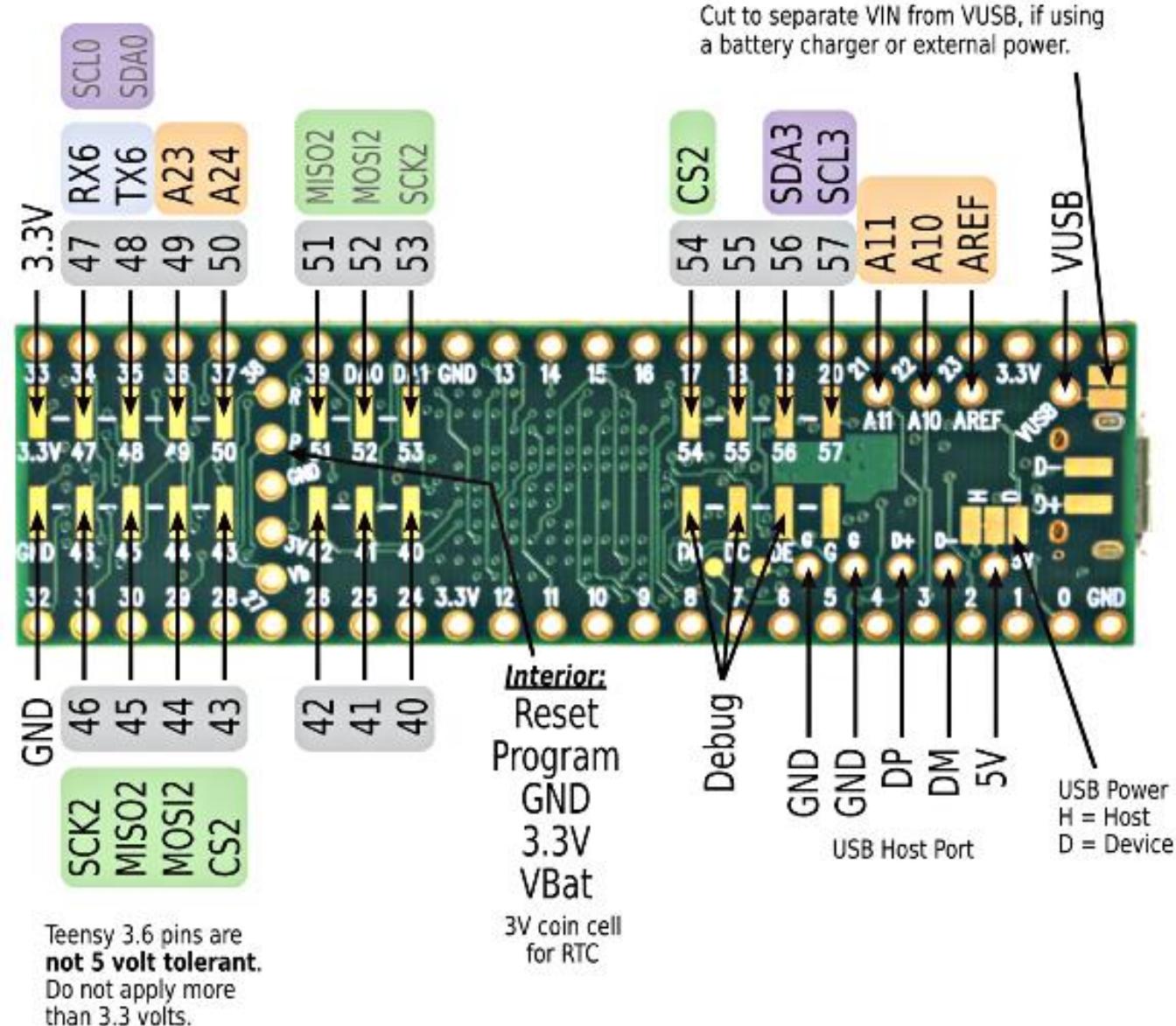
# Debugging Techniques

- Test incrementally
- Test intermediate sub-circuits

# Teensy 3.5

				GND		Vin (3.6 to 6.0 volts)
Touch	MOSI1	RX1	0			Analog GND
Touch	MISO1	TX1	1			3.3V (250 mA max)
			PWM 2			23 A9 PWM Touch
	SCL2	CAN0TX	PWM 3			22 A8 PWM Touch
	SDA2	CAN0RX	PWM 4			21 A7 PWM CS0 mosi1
		miso1	tx1	PWM 5		20 A6 PWM CS0 sck1
				PWM 6		19 A5 SCL0 Touch
	scl0	mosi0	RX3	PWM 7		18 A4 SDA0 Touch
	sda0	miso0	TX3	PWM 8		17 A3 sda0 Touch
		CS0	RX2	PWM 9		16 A2 scl0 Touch
		CS0	TX2	PWM 10		15 A1 CS0 Touch
		MOSI0		11		14 A0 PWM sck0
		MISO0		12		13 (LED) SCK0
				3.3V		GND
				24		A22 DAC1
				25		A21 DAC0
			tx1	26		39 A20
			rx1	27		38 A19 PWM SDA1
				28		37 A18 PWM SCL1
Touch		can0tx	PWM	29		36 A17 PWM
Touch		can0rx	PWM	30		35 A16 PWM
	CS1	RX4	A12	31		34 A15 CAN1RX sda0
	SCK1	TX4	A13	32		33 A14 CAN1TX scl0

# Teensy 3.5 Reverse Side



# Teensy 3.1 vs Teensy 3.5



# Teensy Programming Interface

Connect the Teensy to your laptop via a USB cable

- Be careful not to torque the USB connection on the Teensy

# Demonstration...

# General Program Hints

- Use LEDs to show status information (e.g., to indicate what part of your code is being executed)
- Remember: on the Teensy boards, there is a LED connected to port C, bit 5
- Have one LED blink in some unique way at the beginning of your program
- Go slow:
  - Implement and test incrementally
  - Insert plenty of pauses into your code (e.g., with `delay ()`)

# Project 0

- Summary:
  - Connect 4 LEDs and a switch to your Teensy board
  - Write a program that: waits for the switch to be pressed, then displays an interesting LED flashing pattern
- Details are on the class web page

# Project Completion

See me or the TA for a code review

- Every member of the group must be present
- Every member of the group must demonstrate their own program and downloading to the Teensy
- Deadline: Friday, February 8 @3:30pm

Future projects: we will have more formal coding, documentation and hand-in procedures