

CV_M15_L01

Clustering

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Unsupervised Learning

- Building models that capture the distribution of samples in some high-dimensional space
- So far, we have focused on projecting these feature vectors into some lower-dimensional space
 - Non-linear case: attempted to translate the non-linear manifolds into linear ones
- Useful for better understanding the underlying data & as a basis for preprocessing data

Clustering

- Fundamental idea: we want to infer which samples are similar enough to be considered the same as one-another
- Like classification, this allows us to assign a discrete label to each of our samples
- But: the clustering algorithm determines the labels automatically

Clustering

Clustering algorithms/hyper-parameter choices vary:

- What do we mean by *similar*?
 - How do we measure distance / similarity?
- How similar do two things need to be so that they are considered to be in the same cluster (class)?
- Is the number of clusters fixed or variable?

Clustering

A couple perspectives:

- Represents a form of dimensionality reduction: translating some N-dimensional feature vector into a single enumerated value
- In the simplest cases, we are identifying zero-dimensional manifolds (blobs) in the feature space
 - More advanced methods look at more interesting manifolds

Clustering

- K-Means:
 - Euclidean distance
 - Fixed number of clusters
 - Each cluster effectively has the same shape
- Mixture Models:
 - Use a probability density function as a similarity metric
 - Fixed number of clusters
 - When the PDF includes covariance, then we can handle interesting (local) manifold shapes

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K-Means Clustering

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K-Means Clustering

- Predefine the number of clusters (K)
- Each cluster is parameterized by its center location in the N -dimensional feature space
- Initialize the centers of each cluster in some way
- Repeat:
 - Measure the distance (or similarity) between each sample and each cluster center
 - Assign membership of each sample to a cluster
 - Membership can be hard or soft
 - Update the cluster centers to reflect the member samples

Initialization

Variety of initialization options for the cluster centers:

- Distribution-based: pick centers randomly from within the feature space
 - Uniform sampling
 - Construct a Gaussian distribution over the training set and sample from this distribution
- Sample-based: pick K samples uniformly from the training set

Hard-Boundary Classification

- Each sample is assigned to the cluster that is closest to it
- Even if it is far away from the cluster center...

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Soft-Boundary K-Means Clustering

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Soft K-Means Clustering

Hard boundaries:

- Label is all-or-nothing
- For cluster mean updates: samples near the boundary are just as important as samples far away from the boundary
 - Though, we may be less sure about their “true flavor”
- Easy for the learning algorithm to get into a cycle where a repeatedly pops from one side of the boundary to another

Soft Boundary K-Means Clustering

- Model each sample as probabilistically belonging to each class
 - Probabilistic labels!
- Each sample then contributes to the cluster mean proportionally to this probability

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Soft Boundary K-Means Clustering

- A sample near the boundary between two clusters contributes to both cluster means
 - The balance does not change very much as the sample crosses the boundary
- More stable learning
- Hyper-parameter: beta
 - Small: all classes have interesting probabilities for a given sample
 - Large: one class gets most of the probability

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Example 1: K-Means Clustering

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Example 1: K-Means Clustering

- Scikit-Learn: hard boundary implementation

Live demo

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Example 2: K-Means Clustering

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Example 2: K-Means Clustering

Arrow data set:

- Different parts of the feature space have very differently shaped manifolds
- Variation in the dimensionality (1 vs 2)
- Variation in the sparsity

Live demo

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Multi-Dimensional Gaussian Probability Density Functions

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Representing Clusters

- K-Means Models: similarity metric is spherical:
 - All feature dimensions are treated in the same way
 - No acknowledgement of covariance of features
- What we want:
 - Cluster shapes that acknowledge local manifold structure
 - Some features may vary more than others
 - Some features may covary with others

Multi-Dimensional Gaussian Probability Density Functions

- Density function: given a sample in an N-dimensional space, what is the likelihood of this sample?
- Point in question is N-dimensional
- Output is still a scalar (it is a likelihood)
- We can explicitly capture:
 - Different variances for the different features
 - Covariance across features

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Mixture Distributions

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Mixture Distributions

- Gaussian distributions:
 - All samples are centered around a single mean
 - Likelihood of observing samples drops as we move away from the mean
 - Allow us to represent a single cluster of samples
- But:
 - Many data sets have distinct clusters
 - Gaussian distribution does not capture these situations well

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Learning Gaussian Mixture Distributions

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Learning Gaussian Mixture Distributions

- Given a data set, we need to estimate:
 - Means for all K clusters
 - Covariance matrices for all K clusters
 - Weights
- There is no closed form solution
- But, like soft boundary K-means, we can take an iterative approach

Learning Gaussian Mixture Distributions

Algorithm outline:

1. Guess at the mixture model parameters
2. Probabilistically assign samples to each cluster
3. Re-estimate the mixture model parameters given the sample assignment
4. Repeat starting with #2

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Expectation Maximization Learning Example

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Example 1: EM and Mixture Models

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Example 1: EM and Mixture Models

Five-cluster data set...

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Example 2: EM and Mixture Models

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Example 2: EM and Mixture Models

Arrow data set

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Clustering Wrap-Up

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Clustering Notes

- Soft Boundary & Mixture Model approaches: use probability density functions to describe the clusters
- Soft Boundary K-Means: models cluster location
 - Circular clusters
- Mixture Model: add scaling and covariance
 - Ellipsoidal clusters

Clustering Notes

- Both methods are iterative in nature
 - Lots of local maxima in our likelihood space
- Final solution depends on what our initial guess is
 - Quality of the final solutions can also vary a lot!
- Typical approach: perform the learning process multiple times and keep the best one

Clustering Notes

Hyper-parameters:

- How to make the initial guesses
- Soft-boundary: beta
- Gaussian mixture model: estimates its own shapes
- All require us to specify the number of clusters ahead of time

Clustering Notes

Picking the number of clusters:

- We typically try multiple values
- Regularized cost function:
 - Want to maximize the likelihood of our learned model generating our training data
 - Want to also minimize the number of model parameters that we use (so, keep K small!)
 - Common scorer choices: Bayesian Information Criterion (BIC) or the Akaike Information Criterion (AIC)
 - GaussianMixture class provides these!

Mixture Models

- We can move beyond Gaussian distributions (any PDF can be used!)
- Allows us to better match the manifold shapes of our data set
- Can also work in other metric spaces!
 - For example: PDFs describing 3D orientations

